CONTROLLERS FOR MULTIPLEXED CABINETS WITH STEPPER DRIVER INSIDE

XM678D

-MANUAL FOR THE SW REL. 2.6-

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1. **GENERAL WARNING**

1.1 A PLEASE READ BEFORE USING THIS MANUAL

- This manual is part of the product and should be kept near the instrument for easy and quick reference.
- The instrument shall not be used for purposes different from those described hereunder. It cannot be used as a safety device.
- · Check the application limits before proceeding.
- Dixell SrI reserves the right to change the composition of its products, even without notice, ensuring the same and unchanged functionality.

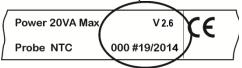
1.2 A SAFETY PRECAUTIONS

- Check the supply voltage is correct before connecting the instrument.
- Do not expose to water or moisture: use the controller only within the operating limits avoiding sudden temperature changes with high atmospheric humidity to prevent formation of condensation
- Warning: disconnect all electrical connections before any kind of maintenance.
- Fit the probe where it is not accessible by the End User. The instrument must not be opened.
- In case of failure or faulty operation send the instrument back to the distributor or to "Dixell S.r.l." (see address) with a detailed description of the fault.
- Consider the maximum current which can be applied to each relay (see Technical Data).
- Ensure that the wires for probes, loads and the power supply are separated and far enough from each other, without crossing or intertwining.

2. BEFORE PROCEEDING

2.1 CHECK THE SW REL. OF THE XM678D

1. Look at the SW rel. of XM678D printed on the label of the controller.



If the SW release is 2.6, proceed with this manual otherwise contact Dixell to get the right manual.

3. GENERAL DESCRIPTION

The XM678D is a microprocessor based controller for multiplexed cabinets suitable for applications on medium or low temperature. It can be inserted in a proprietary LAN with up to 8 different sections which can operate, depending on the programming, as stand alone controllers or following the commands coming from the other sections. The XM678D is provided with 6 relay outputs to control the solenoid valve, defrost - which can be either electrical or hot gas - the evaporator fans, the lights, an auxiliary output and an alarm output and with the stepper valve driver. The device is also equipped with six probe inputs: for temperature control, for control the defrost end temperature, for display and the fourth can be used for application with virtual probe or for inlet/outlet air temperature measurement. Moreover, fifth and sixth probe are used to evaluate and control the superheat. Finally, the XM678D is equipped with the three digital inputs (free contact) fully configurable by parameters. The device is equipped with the HOT-KEY connector that permits to be programmed in a simple way. The optional direct serial output RS485 (ModBUS compatible)

permits a simple XWEB interfacing. RTC is available as options. The HOT-KEY connector can be used to connect X-REP display (Depending on the model).

4. QUICK REFERENCE GUIDE: HOW TO RUN THE SELF ADAPTIVE REGULATION IN 5 STEPS.

 After wiring the XM678D, configure the type of valve, bipolar or unipolar, via tEu (Default tEu = bP: bipolar) and

tEP (Default tEP =0) parameters or through the manual settings. See par. 6.3 for details

NOTE: for Alco EX4, EX5, EX6 tEP = 11

For EX3: tEP = 12

Set the proper gas via Fty parameter. Pre-set gas is R404A.

3. Configure the probes:

- Regulation and evaporator probe are preset as NTC. If another kind of sensors is used, set it via P1c and P2c parameters.
- Superheat evaporator outlet probe is pre-set as Pt1000, if another kind of sensor is used, set it via P6c parameter.
- The PP11 (-0.5-11bar) is pre-set as pressure probe. It operates at relative pressure (Pru = rE).

If you're using a ratiometric transducer, set P5c = 0-5, then use parameters PA4 and P20 to set the range

NOTE: check the pressure gauge reading with the value of dPP, press the UP arrow once to enter the Fast Access Menu. If ok, proceed; otherwise solve the situation before proceeding acting on par. Pru, PA4 and P20.

4. Set the parameters for self adaptive regulation of superheat

NOTE: the parameters Pb (regulation band) and Int (integral time) are automatically calculated by the controller

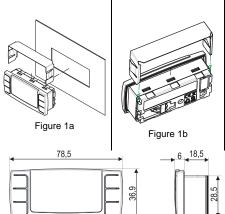
- Set CrE = no, this disable the continuos regulation of the temperature.
 Default is CrE = no.
- Set SSH, superheating setpoint: a value between 4 and 8 is acceptable Default is SSH=8-
- Set AMS = y to start the self adaptive regulation. Default is AMS = y
- Set ATU = y to start the search of the **lowest stable superheat**. Default is ATU = y. This function reduces automatically the setpoint in order to optimize the use of the evaporator, keeping, at the same time, the superheating regulation stable. The minimum allowed SH set point is LSH+2°C.
- Set LSH, low superheating limit: a value between 2-4 is acceptable.
 Default is LSH = 3
- Set SUb, pressure filter: Default is SUb = 10. The value can be increased up to 20 in case of too fast response of the pressure variations.

5. Set the parameters for the temperature regulation

- Set the temperature **setpoint**. Default is -5°C
- Set the differential HY: Default is 2°C.
- If the capacity of the valve is higher than requested, it can be reduced by the par. MNF (Default is 100). A proper setting of MnF will reduce the time that the algorithm takes to reach the stability. MNF value doesn't affect the band witdh

5. INSTALLATION AND MOUNTING

This device can operate without any user interface, but normal application is with Dixell CX660 keyboard.



The CX660 keyboard shall be mounted on vertical panel, in a 29x71 mm hole, and fixed using the special bracket supplied as shown in fig. 1a/1b. The temperature range allowed for correct operation is 0 to 60°C. Avoid places subject to strong vibrations, corrosive gases, excessive dirt or humidity.

The same recommendations apply to probes. Let air circulate by the cooling holes.

6. WIRING DIAGRAM AND CONNECTIONS

Figure 1c

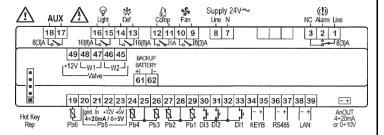
6.1 IMPORTANT NOTE

XM device is provided with disconnectable terminal block to connect cables with a cross section up to 1.6 mm² for all the low voltage connection: the RS485, the LAN, the probes, the digital inputs and the keyboard. Other inputs, power supply and relay connections are provided with screw terminal block or fast-on connection (5.0 mm). Heat-resistant cables have to be used.

Before connecting cables make sure the power supply complies with the instrument's requirements. Separate the probe cables from the power supply cables, from the outputs and the power connections. Do not exceed the maximum current allowed on each relay, in case of heavier loads use a suitable external relay. **N.B.** Maximum

current allowed for all the loads is 16A. The probes shall be mounted with the bulb upwards to prevent damages due to casual liquid infiltration. It is recommended to place the thermostat probe away from air streams to correctly measure the average room temperature. Place the defrost termination probe among the evaporator fins in the coldest place, where most ice is formed, far from heaters or from the warmest place during defrost, to prevent premature defrost termination.

6.2 XM678D



6.3 VALVE CONNECTIONS AND CONFIGURATION

6.3.1 Type of cables and max lenght

To connect the valve to the controller, use only shielded cables with section greater than or equal to 0.823 mm² (AWG18).

A twisted shielded cable with the the above specification is suggested.

Don't connect the shield to any ground, live it floating.

The max distance between an XM controller and a valve must not exceed 10 m.

6.3.2 Valve selection

To avoid possible problems, before connecting the valve configure the driver by making the right changes on the parameters.

- a. Select the kind of motor (tEU parameter)
- check if the valve is present in **tEP parameter table** reported here below.

→ CHECK THE FOLLOWING TABLE FOR A RIGHT SETTING ←

!!!!! In any case, the unique and valid reference has to be considered the datasheet made by valve manufacturer. Dixell cannot be considered responsible in case of valve damaging due to wrong settings!!!!!!

		LSt	uSt	CPP	CHd	Sr	tEu	HSF
tEP	Model	(steps	(steps	(mA*	(mA*	(step/	(bip/	(Half
		*10)	*10)	10)	10)	s)	unip)	/full)
0	Manual settings	Par	Par	Par	Par	Par	Par	Par
1	Danfoss ETS-25/50	7	262	10	10	300	bP	FUL
2	Danfoss ETS-100	10	353	10	10	300	bP	FUL
3	Danfoss ETS- 250/400	11	381	10	10	300	bP	FUL
4	Sporlan SEI .5 to 11	0	159	16	5	200	bP	FUL
5	Sporlan SER 1.5 to 20	0	159	12	5	200	bP	FUL
6	Sporlan SEI 30	0	319	16	5	200	bP	FUL
7	Sporlan SER(I) G,J,K	0	250	12	5	200	bP	FUL
8	Sporlan SEI-50	0	638	16	5	200	bP	FUL
9	Sporlan SEH(I)-100	0	638	16	5	200	bP	FUL
10	Sporlan SEH(I)-175	0	638	16	5	200	bP	FUL

tEP	Model	LSt (steps *10)	uSt (steps *10)	CPP (mA* 10)	CHd (mA* 10)	Sr (step/ s)	tEu (bip/ unip)	HSF (Half /full)
11	Emerson EX4-EX5- EX6	5	75	50	10	350	bP	FUL
12	Emerson EX3	2	32	0	0	50	uР	HAF

If you can see your valve on the table, please select the valve through **tEP parameter.** In this way, you can be sure of a right configuration. About the connection, please pay attention to the following table to have a quick reference on the connection mode for valves of different manufacturer

4 WIRES VALVES (BIPOLAR)

Connection numbering	ALCO EX4/5/6/7/8	SPORLAN SEI-SEH- SER	DANFOSS ETS
45	BLUE	WHITE	BLACK
46	BROWN	BLACK	WHITE
47	BLACK	RED	RED
48	WHITE	GREEN	GREEN

5-6 WIRES VALVES (UNIPOLAR)

Connection numbering	SPORLAN	SAGINOMIYA
45	ORANGE	ORANGE
46	RED	RED
47	YELLOW	YELLOW
48	BLACK	BLACK
49 – Common	GRAY	GRAY

AFTER MAKING THE CONNECTION, PLEASE SWITCH OFF AND ON THE CONTROLLER IN ORDER TO BE SURE OF THE RIGHT POSITIONING OF THE VALVE.

6.4 WIRING CONNECTION OF EMERSON EX3 VALVE

XM678D AND EX3 CONNECTION

The EX3 valve integrates a solenoid valve with posisitive shut off on the top and a stepper valve.

6.4.1 SOLENOID VALVE CONNECTION

- Verify the coil voltage of solenoid valve, and make sure it's the same voltage of relay output.
- b. Set oA1 or oA6 = E3r (solenoid coil of EX3). Be carefull any other setting of the oA1 or oA6 parameter can damage the solenoid valve
- with oA1 = E3r connect the solenoid valve to the terminals 11-12.
 with oA6 = E3r connect the solenoid valve to the terminals 17-18.
- NOTE

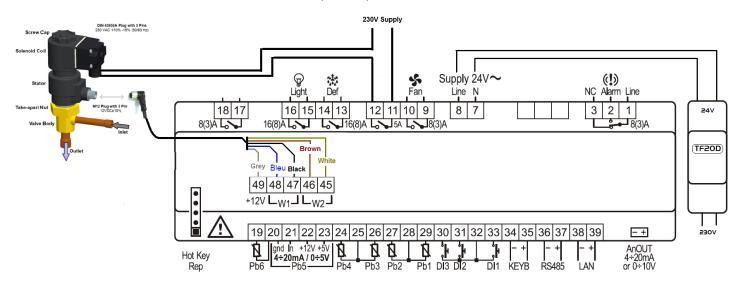
The solenoid coil will be energized every time the regulation temperature is on, and de-energised when the temperature regulation is off, and during the stand by of the controller.

6.4.2 Stepper valve connection

The EX3 unipolar valve has to be connected to the following terminals.

XM678D	EX3
Terminal 49	Grey wire
Terminal 48	Blue wire
Terminal 47	Black wire
Terminal 46	Brown wire
Terminal 45	White wire

E.I. Connection of EX3 with oA1 = E3r and 230V coil of solenoid valve (EX3-C230)



EMERSON

6.5 ABSOLUTE MAXIMUM POWER

XM678D is able to drive a wide range of stepper valves, on the following table are indicated the maximum values of current that the actuator can supply to the stepper wiring. The **TF20D Dixell** transformer has to be used.

NOTE: the electrical power absorption of the valve can be unrelated to refrigeration power that valve has. Before using the actuator, please read the technical manual of the valve supplied by the manufacturer and check the maximum current used to drive the valve in order to verify that they are lower than those indicated below.

LVE PE	BIPOLAR VALVES (4 wires)	Maximum Current 0.9A
₹¥	UNIPOLAR VALVES (5-6 wires)	Maximum Current 0.33A

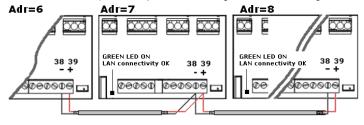
6.6 KEYBOARD DISPLAY CX660



6.7 LAN CONNECTION

Follow next steps to create a LAN connection, which is a necessary condition to perform synchronized defrost (also called master-slave functioning):

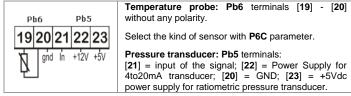
- connect a shielded cable between terminals [38] [-] and [39] [+] for a maximum of 8 sections;
- 2) the Adr parameter is the number to identify each electronic board. Address duplication is not permitted, in this case the synchronized defrost and the communication with monitoring system is not guaranteed (the Adr is also the ModBUS address). For example, a correct configuration is the following:



If the LAN is well connected, the green LED will be ON. If the green LED blinks then the connection is wrongly configured.

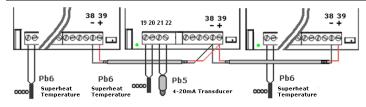
The max distance allowed is 30m

6.8 SENSORS FOR SUPERHEAT CONTROL



Select the configuration of the transducer with parameter P5C

6.9 HOW TO USE ONLY ONE PRESSURE TRANSDUCER OF MULTIPLEXED APPLICATIONS



A working LAN connection is required (green LED lit on all XM678D boards of the same LAN). Connect and configure a pressure transducer only on **one** XM678D of the network. Afterwards, the value of pressure read by the unique transducer connected will be available to each device connected to the same LAN.

By pressing **UP ARROW** button, the user will be able to enter a fast selection menu

dPP = measured pressure (only on master device);

and to read the value of the following parameters:

dP5 = value of temperature obtained from pressure → temperature conversion;

rPP = pressure value read from remote location (only for slave devices).

Examples of error messages:

- dPP = Err → the local transducer read a wrong value, the pressure is out of the bounds of the pressure transducer or the P5C parameter is wrong. Check all these options and eventually change the transducer;
- rPF → the remote pressure transducer is on error situation. Check the status of the onboard GREEN LED: if this LED is OFF the LAN is not working, otherwise check the remote transducer.

LAST CHECKS ABOUT SUPERHEAT

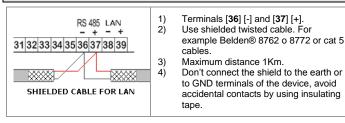
On the fast access menu:

dPP is the value read by the pressure gauge;

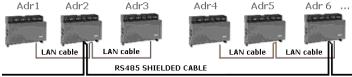
dP6 is the value read by the temperature probe, temperature of the gas on the outlet section of the evaporator:

SH is the value of the superheat. The **nA** or **Err** messages mean that the superheat has no sense in that moment and its value is not available.

6.10 HOW TO CONNECT MONITORING SYSTEM

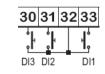


Only one device for each LAN has to be connected to the RS485 connection.



The Adr parameter is the number to identify each electronic board. Address duplication is not permitted, in this case the synchronized defrost and the communication with monitoring system is not guaranteed (the Adr is also the ModBUS address).

6.11 DIGITAL INPUTS



- The terminals from [30] to [33] are all free of voltage;
- Use shielded cable for distance higher than one meter;

For each input, has to be configured: the polarity of activation, the function of the input and the delay of signaling.

The parameters to perform this configuration are i1P, i1F, i1d respectively for polarity, functioning and delay. The i1P can be: cL = active when closed; oP = active when opened. The i1F parameter can be: EAL = external alarm, bAL = serious lock alarm, PAL = pressure switch alarm, dor = door switch, dEF = external defrost, AUS = auxiliary activation command, LiG = light activation, OnF = board On/OFF, FHU = don't use this configuration, ES = day/night, HdY = don't use this configuration. Then there is i1d parameter for delay of activation. For the others digital inputs there are a set of the same parameters: i2P, i2F, i2d, i3P, i3F, i3d.

6.12 ANALOG OUTPUT



- Selectable between 4 to 20mA and 0 to 10Vdc.
- Use CABCJ15 to perform the connections

It's located near the terminal [39] on a 2-pin connector. It's possible to use the output to control anti-sweat heaters through a chopped phase controller XRPW500 (500watt) or family XV...D or XV...K.

7. BATTERY BACK UP CONNECTION

7.1 CONNECTION OF XEC SUPERCAP

XEC Supercap is designed to be used with Dixell products (XM678D, XEV, IEV and others); compatibility with Dixell devices has to be verified in the user manual/technical sheet of the device.

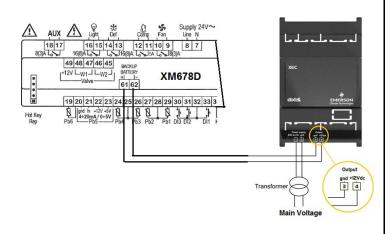
In case of dubt, please contact Dixell Service department.

!!!!! IMPORTANT !!!!!

XEC Supercap and XM678D **must be powered by two different transformers**; the failure of the observance of this rule may result in damage to the XEC Supercap and / or the connected XM678D.

Wiring connection

٠.	g comiconom					
	XM678D	XEC				
	Terminal 61 (+)	Terminal 4 (12Vdc)				
	Terminal 62 (-)	Terminal 3 (gnd)				



7.2 EMERSON ECP-024 CONNECTION

The Emerson ECP-024 rechargeable accumulator can be connected to the XM678D to close the stepper valve in case of power interruption.

Wiring connection

XM678D	ECP-024
Terminal 61 (+)	Terminal +
Terminal 62 (-)	Terminal -

About conditions of use and limitation please refer to the ECP-024 manuals.

8. USER INTERFACE

DIRECT COMMAND INTERFACE



Press and release: Show set point

ON/OFF Press and hold 3": device ON/OFF

ICONS

SET

	Co			
				With icon ON the
Light →	- \	*	\$ ← Fan	output is active, while with blinking icon there
Defrost →	懋	AUX	← Auxiliary relay	is a delay. MEASUREMENT
Energy saving →	(***	Enabled O, but and	
Generic alarm →	(D)	(← Clock / time	are ON depending on the selection.
DURING PROGRAMMING: blink the measurement units of temperature and				

pressure

8.3 KEYBOARD COMMANDS

Single commands:

LĬGHT relay Press light button. **AUX** relav Press down arrow

Manual defrost Press and hold for 3 sec the defrost button ON/OFF Press for 3 sec the ON/OFF button (if the function is

enabled).

Press for 3 sec the ON/OFF button (if the function is **Energy Saving**

enabled).

Double commands:

Double commands.						
∀ +△	Press and hold for about 3 sec to lock (Pon) or unlock (PoF) the keyboard.					
SET + A	Pressed together to exit from programming mode or from menu; on submenus rtC and EEV this combination allow to come back to previous level.					
SET + 🗸	Pressed together for 3 sec allow to access to first level of programming mode.					

8.4 HOW TO MODIFY THE SET POINT FOR AIR TEMPERATURE **REGULATION**

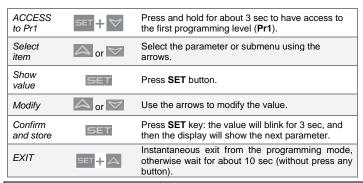
The thermostat set point is the value that will be used to regulate the air temperature. The regulation output is controlled by the electronic valve or by the relay.

BEGIN	SET	Press SET button for 3 sec, the measurement units will blink together.
Value modification	△ or ▽	With the arrows it's possible to change the value within the LS and US parameters value.
EXIT	SET	By pressing SET it is possible to confirm the value that will blink for about 2 sec.

In any case, it is possible to wait for about 10 sec to exit. In order to show the air temperature set is sufficient to press and release the SET button, the value is displayed for about 60 sec.

9. HOW TO PROGRAM THE PARAMETERS (PR1 AND PR2)

The device provide 2 programming levels: Pr1 with direct access and Pr2 protected with a password (intended for experts).

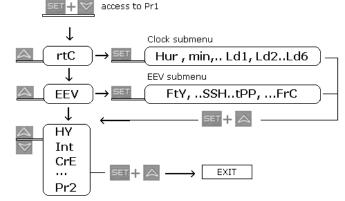


9.1 HOW TO HAVE ACCESS TO "PR2"

- To enter **Pr2** programming menu:

 1. Access to a **Pr1** menu by pressing both **SET+DOWN** keys for 3 sec, the first parameter label will be showed;
 - 2. Press DOWN key till the Pr2 label will be showed, then press SET;
- 3. The blinking PAS label will be showed, wait some seconds;
- 4. Will be showed "0 -" with blinking 0: insert the password [321] using the keys UP and DOWN and confirming with SET key.

GENERAL STRUCTURE: The first two item rtC and EEV are related to submenus with others parameters



- SET+UP keys on rtC or EEV submenus allow coming back to parameter list,
- SET+UP keys on parameter list allow immediate exit.

9.2 HOW TO MOVE PARAMETER FROM PR1 TO PR2 AND VICE

Enter on Pr2; select the parameter; press together [SET + DOWN]; a left side LED ON gives to the parameter the presence on Pr1 level, a left side LED OFF means that the parameter is not present on Pr1 (only Pr2).

FAST ACCESS MENU

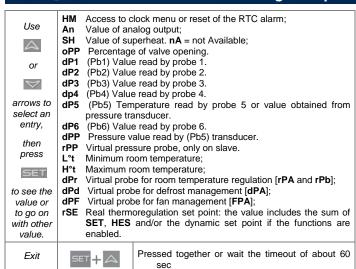
This menu contains the list of probes and some values that are automatically evacuate by the board such as the superheat and the percentage of valve opening. The values: nP or noP stands for probe not present or value not evacuate, Err value out of range, probe damaged not connected or incorrectly configured.

Entering		By press and release the UP arrow . The duration
fast		of the menu in case of inactivity is about 3 min.
access	\sim	The values that will be showed depend on the
menu		configuration of the board.

Dixell

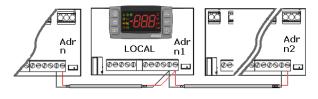
Installing and operating instructions

EMERSON



11. MENU FOR MULTIMASTER FUNCTION: SEC

The function "section" SEC is enabled when icon $\stackrel{\bullet}{\Longrightarrow}$ is lit. It allows entering in the remote programming mode, from a keyboard not physically connected to the board, through the LAN functionality.



Action	Button or display		Notes
Enter menu	A		Press UP arrow for about 3 sec, the icon will be ON.
Waiting for action	SE	С	The menu to change the section will be entered. SEC label will be displayed.
Enter section list	SET		Press SET to confirm. The following list will be available to select the proper network function.
Select proper function	Or	LOC ALL SE1 SEn SE8	To gain access only to the local device. To gain access to all the devices connected to the LAN. To gain access to the device with 1st Adr (*) To gain access to the device with 8th Adr (*)
Confirm	Ontirm		Select and confirm an entry by pressing SET button.
Exit menu	SET-	<u></u>	Press SET and UP together or wait about 10 seconds.

(*) The devices on the LAN are indexed by using the Adr parameter (in ascending order).

EXAMPLES:

- To modify the same parameter values in all the devices connected to the LAN: enter multimaster menu. Select and confirm ALL. Exit from multimaster menu. Enter the programming menu and change the required parameter values. The new values will be changed on all devices connected to the LAN.
- 2. To modify a parameter value in the device with [Adr = 35]: find the relevant indexed section (the one linked to [Adr = 35]). Enter multimaster menu. Select and confirm this section from the multimaster menu. Exit from multimaster menu. Enter the programming menu and change the required parameter value.
- If the alarm nod is present: enter the multimaster menu. Select and confirm the LOC section. Exit from multimaster menu.

AT THE END OF THE PROGRAMMING PROCEDURE, SELECT THE SECTION "LOC". IN THIS WAY THE ICON "HE WILL BE SWITCHED OFF!!

11.1 SYNCHRONIZED DEFROST

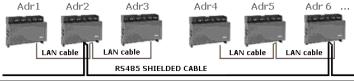
The synchronized defrost allow to manage multiple defrost from different boards connected through the LAN connection. In this way, the boards can perform simultaneous defrosts with the possibility to end them in a synchronized way.

The Adr parameter cannot be duplicated because in this case the defrost cannot be correctly managed.

BEGIN Press for 3 seconds, the **rtC** or other will be showed. The measurement unit blinks.

Find Adr	\triangleright	Press more than once the DOWN arrow to find the Adr parameter, the press SET .
Modify Adr	△ or ▽	Set the value of Adr parameter, then press SET to confirm the parameter.
EXIT	SET + A	Press the two keys together to exit from menu or wait for about 10 seconds.

The **LSn** and **LAn** parameter are only to show the actual settings (read only). Se the following example of configuration:



DAILY DEFROST FROM RTC: [EdF = rtC]

IdF Parameter: for safety reason force the value of Idf at +1 respect to the interval between two Ld parameters. The IdF timer is reinitialized after defrost and at every power-on

DEFROST START: at the time selected by the parameters **Ld1** to **Ld6** or **Sd1** to **Sd6**.

DEFROST END: if the probes reach the **dtE** temperature or for maximum **MdF** time. **SAFETY and RtC or RtF ALARM:** with clock alarm the device will use the parameter **ldF, dtE** and **MdF**.

WARNING: don't set [EdF = rtC] and [CPb = n].

MULTIMASTER DEFROST: all the probes with clock Table for example

Par.	Unit A (RTC)	Unit B (RTC)	Unit C (RTC)
Adr	n	N + 1	N + 2
EdF	rtC (clock)	rtC (clock)	rtC (clock)
ldF	9 hours safety	9 hours safety	9 hours safety
MdF	45 min safety	45 min safety	45 min safety
dtE	12°C safety	12°C safety	12°C safety
Ld1	06:00 1°	06:00 1°	06:00 1°
Ld2	14:00 2°	14:00 2°	14:00 2°
Ld3	22:00 3°	22:00 3°	22:00 3°

12. COMMISSIONING

12.1 CLOCK SETTING AND RTC ALARM RESET

If the clock is present: [EdF = rtC] enable the defrost from rtc [Ld1 to Ld6].

BEGIN	UP arrow (press once) to access the fast access menu					
Display	HM identify the	HM identify the clock RTC submenu; press				
Display	Min = minutes	HUr = hour → press set to confirm/modify Min = minutes → press set to confirm/modify don't use others parameters if present.				
EXIT	Press for about 10 sec. The operation resets talarm.					

Note: the **rtC** clock menu is present also on the second level of parameters. **Warning:** if the board shows the **rtF** alarm, the device has to be changed.

Some parameters have to be checked:

- [1] Superheat temperature probe: Ntc, Ptc, Pt1000 with parameter P6C. The sensor has to be fixed at the end of the evaporator.
- [2] Pressure transducer: [4 to 20mA] or ratiometric P5C = 420 or 5Vr with parameter P5C.
- [3] Range of measurement: check the parameter of conversion PA4 and P20 that are related to the transducer.

TRANSDUCER: [-0.5/7Bar] or [0.5/8Bar abs] the correct setup is relative pressure with PA4 = -0.5 and P20 = 7.0. The [0.5/12Bar abs] the correct setup is relative pressure with PA4 = -0.5 and P20 = 11.00.

Example of virtual pressure with unique [4 to 20mA] or [0 to 5V] transducer:

Param.	XM6x8D_1 XM6x8D_2 + with without transducer transducer		XM6x8D_3+ without transducer
Adr	n	n + 1	n + 2
LPP	LPP = n	LPP = Y	LPP = n
P5C	LAN or not connect the probe	P5C= 420 or 0-5V	LAN or not connect the probe
PA4	Not used	-0.5 bar	Not used
P20	Not used	7.0 bar	Not used

[4] From EEV submenu: select the correct kind of gas with FTY parameter.

[5] Use the following parameters to setup the right valve driving, according to the valve datasheet from the manufacturer.

- Type of Stepper motor: [uP-bP] it permits to select the kind of valve. uP = 5 -6 wires unipolar valves; bP = 4 wires bipolar valves; !!!!! WARNING !!!!! by changing this parameter the valve has to be reinitialized.
- Predefined valve selection: [0 to 10] if [tEP = 0] the user has to modify all the parameters of configuration in order to use the valve. If tEP is different from 0 the device performs a fast configuration of the following parameters: LSt, uSt, Sr, CPP, CHd. To select the right number please read the following table:

tEP	Model	LSt (steps *10)	uSt (steps *10)	CPP (mA* 10)	CHd (mA* 10)	Sr (step/ s)	tEu (bip/ unip)	HSF (Half /full)
0	Manual settings	Par	Par	Par	Par	Par	Par	Par
1	Danfoss ETS-25/50	7	262	10	10	300	bΡ	FUL
2	Danfoss ETS-100	10	353	10	10	300	bΡ	FUL
3	Danfoss ETS- 250/400	11	381	10	10	300	bP	FUL
4	Sporlan SEI .5 to 11	0	159	16	5	200	bΡ	FUL
5	Sporlan SER 1.5 to 20	0	159	12	5	200	bP	FUL
6	Sporlan SEI 30	0	319	16	5	200	bΡ	FUL
7	Sporlan SER(I) G,J,K	0	250	12	5	200	bP	FUL
8	Sporlan SEI-50	0	638	16	5	200	bΡ	FUL
9	Sporlan SEH(I)-100	0	638	16	5	200	bP	FUL
10	Sporlan SEH(I)-175	0	638	16	5	200	bP	FUL
11	Alco EX4-EX5-EX6	5	75	50	10	350	bP	FUL
12	Emerson EX3	2	32	0	0	50	uP	HAF

If tEP is different from 0 previous configuration of LSt, uSt, Sr, CPP and CHd are overwritten.

Kind of motor movement: (HAF: FUL)

HAF = half step. Use this setting for the unipolar valve.

FUL = half step. Use this setting for the bipolar valve.

- Minimum number of steps: [0 to USt] it permits to select the minimum LSt number of steps. At this number of steps the valve should be closed. So it's necessary the reading of manufacturer datasheet to set correctly this parameter. It's the minimum number of steps to stay in advised range of functioning. !!!!! WARNING !!!!! By changing this parameter the valve has to be reinitialized. The device performs this procedure automatically and
- restarts its normal functioning when the programming mode ends.

 Maximum number of steps: [LSt to 800*10] it permits to select the maximum number of steps. At this number of steps the valve should be completely opened. Read the datasheet provided by manufacturer of the valve to set correctly this parameter. It's the maximum number of steps to stay in advised range of functioning. !!!!! WARNING !!!!! By changing this parameter the valve has to be reinitialized. The device performs this procedure automatically and restarts its normal functioning when the programming mode ends.
- Extra step during closing phase: (0 to 255 (*10)) it sets the number of extra steps the controller performs, when the valve is closed at start up, and during the pauses of regulation, to force the closure of the valve.

NOTE: to set ESt the following steps has to be done:

- Set the kind of valve by the parameter tEP. This pre-set the parameters related to the valve
- Set the right value of ESt
- Step rate [10 to 600 step/sec] it's the maximum speed to change step without losing precision (means without losing steps). It's advised to stay under the maximum speed.
- CPP Current per phase (only bipolar valves): [0 to 100*10mA] it's the maximum current per phase used to drive valve. It's used only with bipolar valves.
- Holding current per phase (only bipolar valves): [0 to 100*10mA] it's the current per phase when the valve is stopped for more than 4 minutes. It's used only with bipolar valves

13. KIND OF REGULATION FOR SUPERHEAT: SELF ADAPTIVE OR MANUAL OPERATING MODE

PRESSURE FILTERING - SUB PARAMETER

For a good SH regulation, it's important to use a filtered value of the pressure. This can be done by the parameter Sub. Suggested values:

> From 1-5 evaporators for each racks: Sub = 15 From 6-30 evaporators for each racks: Sub = 10 More than 30 evaporators for each racks: Sub =5

13.2 GENERAL CONSIDERATIONS

The controller is able to regulate the superheat in manual or self adaptive mode, according to the value of the parameter **AMS**, **autotuing enabling**.

- With AMS = n: the normal SH regulation is performed
- With AMS = y: the self adaptive SH regulation is performed

13.3 MANUAL OPERATING MODE - AMS = NO

The temperature and SH regulation can be performed in 2 ways according to the value of the parameter CrE: on/off or continuous. See below in details.Standard temperature regulation

ON/OFF TEMPERATURE REGULATION [CrE = n] 13.3.1

- Temperature regulation is ON/OFF and it depends on the SET point and HY parameter (dfferential) Valve is closed when the temperature reaches the set point and open when the temperature is higher than set point + differential.
- The superheat is regulated to be closer to its set point.
- With more pauses normally also the humidity is bigger. Regulation pauses can be realized using **Sti** and **Std** parameters (during these 4. pauses the valve is closed).

13.3.2 COUNTINUOUS REGULATION OF THE TEMPERATURE [CrE = Y] (with superheat regulation):

- The HY parameter becomes temperature band for PI control. A default good value is 6°C.
- 2. The regulation of injection is continuous and the cooling output is always on. The icon 💥 is always ON excluding the defrost phase.
- The superheat is regulated following the SSH parameter. 3.
- 4. Regulation pauses can be realized using Sti and Std parameters (during these pauses the valve is closed).
- 5. Increasing the Int integral time it is possible to decrease the speed of reaction of the regulator on the HY band.

13.4 SELF ADAPTIVE OPERATING MODE - AMS = YES

Auto-adaptive means to find and maintain the condition of the lowest super heating according to the load and environmental conditions present in a given time on the evaporator.

The parameter AMS enables the self adaptive mode for the superheat regulation. In this functioning the values of Pb and inC parameter are automatically set by the controller according to the kind of applications and the response of the system.

With the AMS = YES, CrE must be set at NO.

The self adaptive algorithm does not affect, the functions related to the forced opening of the valve in special situation such as:

Forced opening of the valve at start of regulation, parameter SFd (percentage) and SFd (time).

MINIMUM STABLE SUPERHEAT SEARCH - AMS = YES, ATU = 13.5 YES

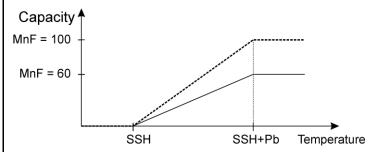
With the parameter ATU, the minimum stable superheat search function is enabled.

With ATU = yES controllers start searching the mimimum stable value for the SH, the minimum admitted value in any case is LSH + 2°C (4°F). Please take it in consideration, before setting LSH value.

13.6 VALVE CAPACITY REDUCING - MNF PARAMETER

Thanks to the parameter MnF it's possible to reduce the capacity of the valve, to fine tune the valve to the evaporator.

The regulation band is not affected from the modification of the MnF parameter. See below the behaviour of the capcity of the valve, when the MnF parameter is adjusted.



NOTE: during the soft start phase (oPE, SFd), MnF parameter is not taken in consideration and the capacity of the valve is set by the parameters oPE and oPd, respectively.

13.7 AUTO ZERO PROCEDURE (GO TO HOME FUNCTIONS).

To prevent any possible wrong position caused by a long period of working for the step valve without closing, the controller after gtH hours, as soon as the opening open percentage is under 20%, will force a "go to home" procedure:

- Close the valve at max speed, till the complete closure is reached.
- Perform extra steps (ESt)
- Re-open to the requested regulation position 3.

This procedure is valid for all the valves, and it has to be done at set speed for each

14. DISPLAY MESSAGES							
Display Causes Notes							
		KEYBOARD					
1	nod	No display: the keyboard is trying to work with another board that is not working or not present	Press for 3 sec UP arrow, enter the SEC menu and select LOC entry.				
2	Pon	Keyboard is unlocked					

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	Display	Causes	Notes	
3	PoF	Keyboard is locked		
4	rSt	Alarm reset	Alarm output deactivated	
5	noP, nP nA	Not present (configuration) Not available (evaluation)		
6	noL The keyboard is not able to communicate with the XM668D or XM678D		Verify the connection. Call the Service	
		ALARM FROM PROBE INPUT		
	P1	Sensor brake down, value out of		
	P2	range or sensor incorrectly	P1: the cooling output works with Con and COF,	
	P3	configured P1C, P2C to P6C.	With defrost probe on error the	
	P4	PPF can be showed by slaves of	defrost is performed only at	
6	P5	pressure that don't receive the	interval.	
	P6	value of pressure.	For P5 , P6 and PPF : the	
	PPF	CPF is showed when the remote	percentage of the valve	
		probe 4 is not working.	opening is fixed at PEO value.	
	CPF			
		TEMPERATURE ALARM	Outputs unchanged	
7	HA	Temperature alarm from parameter ALU on probe rAL .	Outputs unchanged.	
8	LA	Temperature alarm from parameter	Outputs unchanged.	
_		ALL on probe rAL.		
9	"HAd "LAd"	Defrost high temperature Defrost low temperature	Outputs unchanged. Outputs unchanged.	
10 11	"FAd"	Fan low temperature	Outputs unchanged.	
12	"HAF"	Fan high temperature	Outputs unchanged.	
		DIGITAL INPUT ALARM		
		Door open alarm from input i1F,	Cooling relay and fan follow the	
13	dA	i2F or i3F = after delay d1d, d2d or d3d.	odc parameter. Cooling restart as specified on rrd parameter.	
		Generic alarm from digital input	as specified on ITG parameter.	
14	EA	i1F, i2F, i3F = EAL.		
15	CA	Severe alarm of regulation lock from digital input i1F, i2F, i3F = bAL.	Regulation output OFF.	
16	PAL	Pressure switch lock i1F, i2F o i3F = PAL.	All the outputs are OFF.	
		ELECTRONIC VALVE ALARM		
4-	1.00	Minimum operating pressure	The valve output increases its	
17	LOP	threshold from LOP parameter.	opening of dML quantity every second.	
		Maximum aparating process	The valve output decreases its	
18	MOP	Maximum operating pressure threshold from MOP parameter.	opening of dML quantity every	
		and store in the parameter.	second. The valve will be closed: the	
19	LSH	Low superheating from LSH parameter and SHd delay.	alarm will be showed after SHd delay.	
20	нѕн	High superheating from HSH parameter and SHd delay.	Only display.	
		CLOCK ALARM		
21	rtC	Clock settings lost.	Defrost will be performed with IdF till restoring the settings of RTC.	
22	rtF	Clock damaged.	Defrost will be performed with IdF.	
		OTHERS		
23	EE	EEPROM serious problem.	Output OFF.	
24	Err	Error with upload/download parameters.	Repeat the operation.	
25	End	Parameters have been correctly transferred.		

14.1 ALLARM RECOVERY

Probe alarms **P1**, **P2**, **P3** and **P4** start some seconds after the fault in the related probe; they automatically stop some seconds after the probe restarts normal operation. Check connections before replacing the probe.

Temperature alarms HA, LA, HA2 and LA2 automatically stop as soon as the temperature returns to normal values.

Alarms EA and CA (with i1F = bAL) recover as soon as the digital input is disabled. Alarm CA (with i1F = PAL) recovers only by **switching off and on** the instrument.

15. USE OF THE PROGRAMMING HOT-KEY

The XM units can UPLOAD or DOWNLOAD the parameter list from its own E2 internal memory to the **HOT-KEY** and vice-versa through a TTL connector. Using **HOT-KEY the Adr will not changed**.

15.1 DOWNLOAD (FROM THE HOT-KEY TO THE INSTRUMENT)

- Turn OFF the instrument by means of the ON/OFF key, insert the HOT-KEY and then turn the unit ON.
- 2. Automatically the parameter list of the HOT-KEY is downloaded into the controller memory: the doL message is blinking. After 10 seconds the instrument will restart working with the new parameters. At the end of the data transfer phase the instrument displays the following messages: End for right programming. The instrument starts regularly with the new programming. Err for failed programming. In this case turn the unit off and then on if you want to restart the download again or remove the HOT-KEY to abort the operation.

15.2 UPLOAD (FROM THE INSTRUMENT TO THE HOT-KEY)

- 1. When the XM unit is ON, insert the HOT-KEY and push "UP" key
- 2. The UPLOAD begins; the **uPL** message is blinking.
- Remove the HOT-KEY. At the end of the data transfer phase the instrument displays the following messages: End = right programming;

Err = failed programming. In this case push **SET** key if you want to restart the programming again or remove the not programmed **HOT-KEY**.

16. CONTROLLING LOADS

16.1 THE COOLING OUTPUT

The regulation is performed according to the temperature measured by the thermostat probe that can be physical probe or virtual probe obtained by a weighted average between two probes following the formula:

value_for_room_regulation = (rPA*rPE + rPb*(100-rPE))/100

If the temperature increases and reaches set point plus differential the solenoid valve is opened and then it is closed when the temperature reaches the set point value again.

In case of fault in the thermostat probe the opening and closing time of solenoid valve is configured by **Con** and **CoF** parameters.

16.2 STANDARD REGULATION AND CONTINUOUS REGULATION

The temperature regulation can be performed in three ways: the goal of the first way (standard regulation) is reaching the best superheat via a classic temperature regulation obtained using hysteresis. The second way permits to use the valve to realize an high performance temperature regulation with a good factor of superheat precision. This second possibility, it can be used only in centralized plants and it is available only with electronic expansion valve by selecting [CrE = Y] parameter. The third kind of regulation has been thought to be used with vales called evaporator valves [CrE = EUP], in this configuration the valve is placed at the end of the evaporator. In any case, the regulation is performed via PI regulator that gives the opening percentage to the valve.

Standard regulation: [CrE = n]

In this case, the **HY** parameter is the differential for standard ON/OFF regulation. In this case the **int** parameter is neglected.

Continuous regulation: [CrE = Y]

In this case, the HY parameter is the proportional band of PI in charge of room temperature regulation and we advise to used at least [HY = 6.0°C/12°F]. The int parameter is the integral time of the same PI regulator. Increasing int parameter the PI regulator become slowly in reaction and of course is true vice versa. To disable the integral part of regulation you should set [int = 0].

Evaporator valves: [CrE = EUP]

In this case, the system performs a regulation of the temperature without taking in consideration the superheat (in fact the valve is at the end of the evaporator). The **HY** parameter is the proportional band for the temperature regulation and **int** is the integral time for the regulation.

The proportional action is performed only when the compressor relay is on. In this situation there is no superheat regulation.

16.3 DEFROST

Defrost starting

In any case, the device check the temperature read by configured defrost probe before starting defrost procedure, after that:

- (If RTC is present)Two defrost modes are available through the tdF parameter: defrost with electrical heater and hot gas defrost. The defrost interval is controlled by parameter EdF: (EdF = rtC) defrost is made in real time depending on the hours set in the parameters Ld1 to Ld6 in workdays and in Sd1 to Sd6 on holidays; (EdF = in) the defrost is made every ldF time.
- Defrost cycle starting can be operated locally (manual activation by means of the keyboard or digital input or end of interval time) or the command can come from the Master defrost unit of the LAN. In this case the controller will operate the defrost cycle following the parameters it has programmed but, at the end of the drip time, will wait that all the other controllers of the LAN finish their defrost cycle before to re-start the normal regulation of the temperature according to **dEM** parameter.
- Every time any of the controller of the LAN begin a defrost cycle it issue the command into the network making all the other controllers start their own cycle. This allows a perfect synchronization of the defrost in the whole multiplexed cabinet according to **LMd** parameter.

Defrost ending

- When defrost is started via rtC, the maximum duration of defrost is obtained from Md parameter and the defrost end temperature is obtained from dtE parameter
- If dPA is present and [d2P = Y], the instrument stops the defrost procedure when dPA is higher than dtE temperature.

At the end of defrost the drip time is controlled through the Fdt parameter.

16.4 FANS

CONTROL WITH RELAY

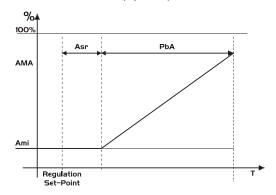
The fan control mode is selected by means of the FnC parameter:

C-n = running with the solenoid valve, OFF during the defrost;

- C-Y = running with th1e solenoid valve, ON during the defrost;
- O-n = continuous mode, OFF during the defrost; O-Y = continuous mode, ON during the defrost.

An additional parameter **FSt** provides the setting of temperature, detected by the evaporator probe, above which the fans are always OFF. This can be used to make sure circulation of air only if his temperature is lower than set in **FSt**.

CONTROL WITH ANALOG OUTPUT (if present)



The modulating output [trA = rEG] works in proportional way (excluding the first AMt seconds where the fans speed is the maximum.

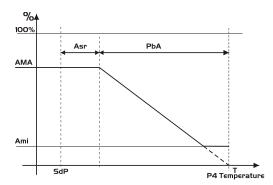
The regulation set point is relative to regulation set point and is indicated by ASr, the proportional band is always located above [SET + ASr] value and its value is PbA. The fans are at minimum speed AMi when the temperature read by fan probe is [SET + ASr] and the fan is at maximum speed (AMA) when the temperature is [SET + ASr + PbA].

16.5 ANTI SWEAT HEATERS

The anti-sweat heater regulation can be performed with on board relay (if **OA6 = AC**) or with the analog output (if present by setting **trA = AC**). However the regulation can be performed in two ways:

- Without real dew-point information: in this case the default value for dewpoint is used (SdP parameter).
- Receiving dew-point from XWEB5000 system: the SdP parameter is overwritten when valid value for dew-point is received from XWEB. In case of XWEB link is lost, SdP is the value that will be used for safety.

The best performance can be obtained using probe 4. In this case, the regulation follows the chart:



Probe 4 should be placed on the showcase glass. For each cabinet can be used only one probe 4 (P4) sending its value to the others section that are connected to the LAN.

HOW TO WORK WITH PROBE 4 THROUGH THE LAN:

Param.	XM6x8D_1 Without probe 4	XM6x8D_2 + with probe 4	XM6x8D_3+ Without probe 4		
Adr	n	n + 1	n + 2		
LCP	LCP = n	LCP = Y	LCP = n		
P4C	LAN or not connect the probe	P4C = NTC, PtC or PtM	LAN or not connect the probe		
trA	trA = AC if the device has the analog output				
OA6	OA6 = AC if the device will use the AUX relay for regulation				

HOW TO WORK WITHOUT PROBE 4:

Param.	XM6x8D Without probe 4
P4C	nP
AMt	% of ON

In this case, the regulation is performed by switching on and off the auxiliary relay on a 60 minutes time base. The ON time will be the AMt value, so that the relay will be ON for AMt minutes and OFF for [60-AMt] minutes.

In case of P4 error or if P4 is absent the output is at **AMA** value for the **AMt** time then the output is at 0 value for the time [**255 – AMt**] time performing a simple PWM modulation.

16.6 AUXILIARY OUTPUT

The auxiliary output is switch ON and OFF by means of the corresponding digital input or by pressing and releasing the down arrow key.

17. TECHNICAL DATA

CX660 keyboard

Housing: self extinguishing ABS

Case: CX660 fascia 35x77 mm; depth 18mm

Mounting: panel mounting in a 29x71 mm panel cut-out

Protection: IP20 Frontal protection: IP65

Power supply: from XM600 power module Display: 3 digits, red LED, 14.2 mm high

Optional output: buzzer

Power modules

Case: 8 DIN

Connections: Screw terminal block ≤ 1.6 mm² heat-resistant wiring and 5.0mm fast-

on or screw terminals. **Power supply:** 24Vac

Power absorption: 20VA max.

Inputs: up to 6 NTC; PTC; Pt1000 probes. Max cable length 15m

Digital inputs: 3 free of voltage. Max cable length 15m Relay outputs: <u>Total current on loads MAX. 16A.</u> Solenoid Valve: relay SPST 5A, 250Vac Defrost: relay SPST 16A, 250Vac Fan: relay SPST 8A, 250Vac

Fan: relay SPST 8A, 250Vac Light: relay SPST 16A, 250Vac Alarm: SPDT relay 8A, 250Vac Aux: SPST relay 8A, 250Vac

Outputs for valve: bipolar or unipolar valves.

Max distance between controller and valve: up to 10m with shilded twisted cables,

AWG 18 (0.823mm²) or less.

Max length for LAN:: up to 30m with shilded twisted cables, AWG 20 (0.51mm²) or less.

Optional output (AnOUT) DEPENDING ON THE MODELS:

PWM / Open Collector outputs: PWM or 12Vdc max 40mA

Analog output: 4 to 20mA or 0 to 10V
 Serial output: RS485 with ModBUS - RTU and LAN
 Data storing: on the non-volatile memory (EEPROM)
 Kind of action: 1B; Pollution degree: normal
 Software class: A

Operating temperature: 0 to 60°C (32 to 140°F) Storage temperature: -25 to 60°C (-13 to 140°F) Relative humidity: 20 to 85% (no condensing)

Measuring and regulation range:

NTC probe: -40 to 110°C (-58 to 230°F) PTC probe: -50 to 150°C (-67 to 302°F) Pt1000 probe: -100 to 100°C (-148 to 212°F)

Resolution: 0.1°C or 1°C or 1°F (selectable).

Accuracy (ambient temp. 25°C): ±0.5 °C ±1 digit.



18. DEFAULT PARAMETER MAP

The numbers of the first column are simple indexes that are unrelated to the position on the device menu. The total amount of parameters can be different depending on the applications. **SUBMENUS**: the parameters O1...O24 of the clock belongs to **rtC** label; V1...V30 **ELECTRONIC VALVE** belongs to EEV.

	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
			CLOCK AND DEFROST By pressing		
Φ	rtC		SET it's possible to enter on RTC submenu		Access to CLOCK submenu (if present)
(СьР		RTC presence		Y = the optional RTC board is used. N = the optional RTC board is not used even if mounted
(Hur		Hours.		-
(Min		Minutes.		-
(dAY		Day of the week.	Sun(0); SAt(6)	-
(Hd1	nU	First weekly day.	Sun(0); SAt(6); nu(7)	Set the first day of the week which follows the holiday times.
(Hd2	nU	Second weekly day.	Sun(0); SAt(6); nu(7)	Set the second day of the week which follows the holiday times.
(Hd3	nU	Third weekly day.	Sun(0); SAt(6); nu(7)	Set the third day of the week which follows the holiday times. During the Energy Saving cycle the set point is increased by the
()	iLE	0.0	Energy saving cycle start during workdays.	0.0 to 23h50min (143)	value in HES so that the operation set point is [SET + HES] . Format : hours.10min, resolution : 10min.
(()	dLE	0.0	Energy saving cycle length during workdays.	0.0 to 24h00min (144)	Set the duration of the Energy Saving cycle on workdays. Format: hours.10min, resolution: 10min.
(\$)	iSE	0.0	Energy saving cycle start during holidays.	0.0 to 23h50min (143)	Format: hours.10min, resolution: 10min.
(*)	dSE	0.0	Energy saving cycle length during holidays.	0.0 to 24h00min (144)	Format: hours.10min, resolution: 10min.
((HES	0.0	Temperature increasing during Energy Saving cycle (Day/Night).	[-30.0°C to 30.0°C] [-54°F to 54°F]	Set the increasing value of the set-point during the Energy Saving cycle.
(Ld1	6.0	Workdays First defrost start.	0.0 to 23h50min (143) nU(144)	
(Ld2	13.0	Workdays Second defrost start.	Ld1 to 23h50min (143) nU(144)	Workdays defrost start: [Ldn to 23h50min] these parameters
(Ld3	21.0	Workdays Third defrost start.	Ld2 to 23h50min (143) nU(144)	set the beginning of the eight programmable defrost cycles during workdays. Ex: when [Ld2 = 12.4] the second defrost starts at
(Ld4	nU	Workdays Fourth defrost start.	Ld3 to 23h50min (143) nU(144)	12.40 during workdays. nU = not used.
(Ld5	nU	Workdays Fifth defrost start.	Ld4 to 23h50min (143) nU(144)	Format: hours.10min, resolution: 10min.
(Ld6	nU	Workdays Sixth defrost start.	Ld5 to 23h50min (143) nU(144)	
(Sd1	6.0	Holidays First defrost start.	0.0 to 23h50min (143) nU(144)	
(Sd2	13.0	Holidays Second defrost start.	Sd1 to 23h50min (143) nU(144)	Holidays defrost start: [Sdn to 23h50min] these parameters set
(Sd3	21.0	Holidays Third defrost start.	Sd2 to 23h50min (143) nU(144)	the beginning of the eight programmable defrost cycles on holidays. Ex: when [Sd2 = 3.4] the second defrost starts at 3.40
(Sd4	nU	Holidays Fourth defrost start.	Sd3 to 23h50min (143) nU(144)	on holidays. nU = not used.
(Sd5	nU	Holidays Fifth defrost start.	Sd4 to 23h50min (143) nU(144)	Format: hours.10min, resolution: 10min.
(Sd6	nU	Holidays Sixth defrost start.	Sd5 to 23h50min (143) nU(144)	
(Lo1	nU	Workdays First light switch.	0.0 to 23h50min (143) nU(144)	
(Lo2	nU	Workdays Second light switch.	Lo1 to 23h50min (143) nU(144)	
(Lo3	nU	Workdays Third light switch.	Lo2 to 23h50min (143) nU(144)	Formet: hours 10min recolution: 10min
(Lo4	nU	Workdays Fourth light switch.	Lo3 to 23h50min (143) nU(144)	Format: hours.10min, resolution: 10min.
(Lo5	nU	Workdays Fifth light switch.	Lo4 to 23h50min (143) nU(144)	
(Lo6	nU	Workdays Sixth light switch.	Lo5 to 23h50min (143) nU(144)	
(dLo	0.0	Light on time during workdays.	0.0 to 24h00min (144)	Set the duration of the light on time on workdays. Format: hours.10min, resolution: 10min.
(So1	nU	Holidays First light switch.	0.0 to 23h50min (143) nU(144)	
(So2	nU	Holidays Second light switch.	So1 to 23h50min (143) nU(144)	
(So3	nU	Holidays Third light switch.	So2 to 23h50min (143) nU(144)	Format: hours.10min, resolution: 10min.
(So4	nU	Holidays Fourth light switch.	So3 to 23h50min (143) nU(144)	Tornat. Hours. formin, resolution. formin.
(So5	nU	Holidays Fifth light switch.	So4 to 23h50min (143) nU(144)	
(So6	nU	Holidays Sixth light switch.	So5 to 23h50min (143) nU(144)	
(dSo	0.0	Holidays Sixth defrost start.	0.0 to 24h00min (144)	Set the duration of the light on time on holidays. Format: hours.10min, resolution: 10min.
P	EEU		ELECTRONIC VALVE		By pressing SET you can enter electronic expansion valve submenu.
P	FtY	404	Kind of gas.	R22(0); 134(1); 404(2); 407(3); 410(4); 507(5); CO2(6)	Type of gas used by plant. Fundamental parameter for correct functioning of all system.
P	Atu	Y	Minimum STABLE superheat search	No; yES	This parameter enables the search of the minimum stable superheat. The lowest admitted value is LSH+2°C

	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
•	AMS	Y	Self self adaptive SH regulation enabling	No; yES	This parameter enables the self adaptive regulation of the superheat. CrE = no must to be set, when this function is enabled.
P	SSH	8.0	Superheat set point.	[0.1°C to 25.5°C] [1°F to 45°F]	This is the value used to regulate superheat.
•	Pb	8	Proportional band.	[0.1°C to 60.0°C] [1°F to 108°F]	The valve changes its opening on the band [SSH, SSH + Pb]. At SSH value of superheat the valve will be at 0% (without integral contribution) and at [SSH + Pb] value of superheat the valve will be at MnF. For values bigger than [SSH + Pb] the valve is completely opened.
P	rS	0	Proportional band reset	[-12.0°C to 12.0°C]	It allows to move the regulation band, above or below the SH set point.
P	inC	200	Integration time for superheat regulation.	0 to 255s	-
?	PEO	50	Valve opening in case of error on probes P5 or P6.	0 to 100%	If a temporary probe error occurs, valve opening percentage is PEo until PEd time is elapsed.
P	OPE	85	Start opening percentage for the time SFd. It's not limited by the MnF parameter	0 to 100%	Opening valve percentage when start function is active. This phase duration is SFd time.
P	SFd	0.1	Duration of soft start phase with opening at OPE .	0.0 to 42min00sec (252)	Set start function duration and post-defrost duration. During this phase the alarms are neglected. Format: min.10sec, resolution: 10sec.
P	OPd	85	Valve opening percentage during hot gas defrost. It's not limited by the MnF parameter.	0 to 100%	Opening valve percentage during hot gas defrost. During hot gs defrost there is not SH control.
•	MnF	100	Maximum percentage of opening admitted (during normal functioning).	0 to 100%	During regulation it sets the maximum valve opening percentage. This value is not used during the SFd phase (soft start) and during hot gas defrost, where the fixed percentace of the valve opening is set by oPd.
•	Fot	nU	Manual opening.	0 to 100% nU	It permits to force the valve opening to the specified value. This value overwrites the one calculated by PID algorithm. !!!! WARNING!!!! It must be [Fot = nU] to have correct superheat regulation.
•	PA4	-0.5	Probe value at 4mA or at 0V.	Meas Unit Range BAR [PrU=rE] -1.0 to P20 [PrU=Ab] 0.0 to P20 PSI [PrU=rE] -14 to P20 [PrU=Ab] 0 to P20 dKP [PrU=rE] -10 to P20 [PrU=Ab] 0 to P20	Value of pressure at 4mA for current probe [4 to 20mA] or value at 0V for ratiometric probes. The value is absolute or relative according to PrU parameter.
•	P20	11.0	Probe value at 20mA or at 5V.	Meas Unit Range BAR [PrU=rE] PA4 to 50.0 [PrU=Ab] PA4 to 50.0 PSI [PrU=rE] PA4 to 725 [PrU=Ab] PA4 to 725 dKP [PrU=FE] PA4 to 500 [PrU=Ab] PA4 to 500	Value of pressure at 20mA for current probe [4 to 20mA] or value at 5V for ratiometric probes. The value is absolute or relative according to PrU parameter.
P	LPL	-0.5	Lower Pressure Limit for superheat regulation.	PA4 to P20	EXPERT: when suction pressure goes down the lower bound LPL, superheat regulation will use a fixed pressure value. Otherwise, the normal pressure value will be used (according to PrU parameter).
P	МОР	11.0	Maximum operating pressure threshold and valve closing of dML value.	LOP to P20	If suction pressure exceeds maximum operating pressure value, the instrument will signal this situation giving the MOP alarm (according to PrU parameter).
•	LOP	-0.5	Minimum operating pressure threshold and valve opening of dML value.	PA4 to MOP	If suction pressure exceeds minimum operating pressure value, the instrument will signal this situation giving the LOP alarm (according to PrU parameter).
•	dML	30	Delta [MOP - LOP].	0 to 100%	Until MOP alarm is active, the valve will close, every second, of a value equal to the dML percentage. Until LOP alarm is active, the valve will open, every second, of a value equal to the dML percentage.
P	MSH	60.0	Maximum superheat alarm threshold.	[LSH to 80.0°C] [LSH to 144°F]	If superheat value exceeds MSH value, the display will show the MSH message until delay time SHd will expire.
•	LSH	3.0	Minimum superheat alarm threshold.	[0.0°C to MSH] [0°F to MSH]	If the superheat value is lower than LSH during the SHd delay time, then the display will show the message LSH. As soon as the superheat value is lower than LSH value, the valve will close immediately, without waiting the SHd delay time (to avoid evaporator flooding).
P	SHY	1.0	Hysteresis for superheat alarm recovery [MSH – SHY] and [LSH + SHY].	[0.1°C to 25.5°C] [1°F to 45°F]	-
•	SHd	3.0	Delay of superheat alarm signaling.	0.0 to 42min00sec (252)	If a superheat alarm occurs, the delay time SHd will have to expire before the controller shows an alarm. Format : min.10sec, resolution : 10sec.
•	FrC	0	Integration additive constant (Fast-recovery).	0 to 100s	It permits to decrease faster the integral action when SH value is below the set-point. With higher values the valve closes faster. If [FrC = 0] fast recovery function is disabled.
P	Sub	10	Pressure filter	0÷100	It uses the last average values of the pressure to calculate the superheat.
P	tEP	nU	Predefined valve selection.	nU to 10	See par. 6.3. nU = manual setting.
P	tEU	bP	Kind of valve.	uP; bP	uP = unipolar valve (5-6 wires);
-	HSF	FUL	Kind of motor movement	HAF; FUL	bP = bipolar valve (4 wires). HAF = half step. Use this setting for the unipolar valve. FUL = half step. Use this setting for the bipolar valve.

	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
P	LSt	0	Minimum number of steps where the valve can be considered as completely	0 to USt (* 10)	For manual adjusting of the valve.
P	USt	0	closed. Maximum number of steps that can be	` ,	, ,
P		0	performed.	LSt to 800 (* 10)	For manual adjusting of the valve. Extra steps done by the valve during closing phase to assure the
	ESt C-		Extra steps in closing phase Step rate: is the speed to change step. A	0 to 255(*10)	valve closes completely
P	Sr	10	too high value causes a wrong driving. Current per phase during bipolar valve	10 to 600 (steps/sec)	For manual adjusting of the valve.
•	СРР	0	driving. Current per phase to maintain the actual	0 to 100 (* 10mA)	For manual adjusting of the valve.
•	CHd	0	position (Holding current).	0 to 100 (* 10mA)	For manual adjusting of the valve.
•	GtH	0	Autozero function	0÷15h	To prevent any possible wrong position caused by a long period without closing the valve, the controller after gtH hours, as soon as the opening open percentage is under 20%, will force complete closer of the valve, and then will restart working.
			REGULATION		If [CrE = n] then HY is the hysteresis for ON/OFF
*	НҮ	2.0	Differential.	[0.1°C to 25.5°C] [1°F to 45°F]	thermoregulation. If [CrE = Y] or [CrE = EUP] then HY is the proportional band for temperature PI controller. On these cases the value should be greater than 5°C.
*	int	150	Integral time for room temperature regulation.	0 to 255s	This value is used only when [CrE = Y] or [CrE = EUP]. It's the integral time for thermoregulation: high values mean slower regulation. 0 (zero) = no integral action.
*	CrE	n	Continuous regulation activation.	n(0); Y(1); EUP(2)	With [CrE = Y] or [CrE = EUP] the regulation become PI, HY become a band and int an integral time. n = standard regulation; Y = continuous regulation, to be used only in centralized plants; EUP = evaporator valves (see par. 16.2).
*	LS	-30.0	Minimum set point.	[-55.0°C to SET] [-67°F to SET]	Set the minimum acceptable value for the set-point.
*	US	20.0	Maximum set point.	[SET to 150.0°C] [SET to 302°F]	Set the maximum acceptable value for the set-point.
*	odS	0	Outputs activation delay at start up.	0 to 255min	This function is enabled at the initial start up of the instrument and inhibits any output activation for the period of time set in this parameter (N.B. : AUX and Light can work).
*	AC	0	Anti-short cycle delay.	0 to 60min	Interval between the solenoid valve stop and the following restart.
*	CCt	0.0	Continuous cycle duration.	0.0 to 24h00min (144)	Compressor ON time during continuous cycle: allows to set the length of the continuous cycle: compressor stays on without interruption for the CCt time. It can be used, for instance, when the room is filled with new products. Format: hours.10min, resolution: 10min.
*	ccs	0.0	Continuous cycle set point.	[-55.0°C to 150.0°C] [-67°F to 302°F]	Set point for continuous cycle: used value during the continuous cycle.
*	Con	15	Compressor ON time with faulty probe.	0 to 255min	Solenoid valve ON time with faulty probe: time during which the solenoid valve is active in case of faulty thermostat probe.
*	CoF	30	Compressor OFF time with faulty probe.	0 to 255min	With COn = 0 solenoid valve is always OFF. Solenoid valve OFF time with faulty probe: time during which the solenoid valve is off in case of faulty thermostat probe. With COF = 0 solenoid valve is always active.
888	CF	°C	Temperature measurement unit.	°C(0); °F(1)	°C = Celsius; °F = Fahrenheit. !!! WARNING!!! When the measurement unit changes, all parameters with temperature values will have to be checked.
*	PrU	rE	Pressure Mode.	rE(0); Ab(1)	It defines the mode to evaluate the pressure values. !!! WARNING !!! PrU value is used for all the pressure parameters. If [PrU = rE] all pressure parameters are in relative pressure unit, if [PrU = Ab] all pressure parameters are in absolute pressure unit.
-888	PMU	bAr	Pressure measurement unit.	bAr(0); PSI(1); MPA(2)	It selects the pressure measurement units. MPA means the value of pressure measured by kPA*10.
888	PMd	PrE	Pressure probe visualization	tEM, PrE	It selects the visualization of pressure probe (P5): tEM = temperature; PrE = pressure
-888≡	rES	dE	Resolution (only °C).	dE; in	It sets decimal point display. in = 1°C; dE = 0.1 °C.
-888≡	Lod	tEr	Local display: default display.	nP(0); P1(1); P2(2); P3(3); P4(4); P5(5); P6(6); tEr(7); dEF(8)	It selects which probe is displayed by the instrument. nP = no probe; P1, P2, P3, P4, P5, P6, tEr = virtual probe for thermostat; dEF = virtual probe for defrost.
888	rEd	tEr	Remote display: default display.	nP(0); P1(1); P2(2); P3(3); P4(4); P5(5); P6(6); tEr(7); dEF(8)	It selects which probe is displayed by the X-REP. nP = no probe; P1, P2, P3, P4, P5, P6, tEr = virtual probe for thermostat; dEF = virtual probe for defrost.
-888 ≡	dLY	0	Display delay.	0.0 to 24h00min (144)	When the temperature changes, the display will be updated of 1°C / 1°F when delay time expires. Format: min.10sec, resolution: 10sec.
*	rPA	P1	Regulation probe A.	nP(0); P1(1); P2(2); P3(3); P4(4); P6(5)	First probe used to regulate room temperature. If [rPA = nP] the regulation is performed with real value of rPb.
*	rPb	nP	Regulation probe B.	nP(0); P1(1); P2(2); P3(3); P4(4); P6(5)	Second probe used to regulate room temperature. If [rPb = nP] the regulation is performed with real value of rPA.
*	rPE	100	Virtual probe percentage (room temperature).	0 to 100%	It defines the percentage of the rPA respect to rPb . The value used to regulate room temperature is obtained by:
			DEFROST		value_for_room = (rPA*rPE + rPb*(100-rPE))/100

参 dl 参 tc 参 dd d	dPA dPb dPE tdF tdF EdF dtE idF dSd dFd dAd Fdt	P2 nP 100 EL in 8.0 6 45 0 rt 30	Defrost probe A. Defrost probe B Percentuale prima sonda sbrinamento Defrost kind. Defrost mode. End defrost temperature on probe A (dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request. Display during defrost. Display delay.	nP(0); P1(1); P2(2); P3(3); P4(4); P6(5) nP(0) - P1(1) - P2(2) - P3(3) - P4(4) - P5(5) 0 ÷ 100 (100=dPA, 0=dPb) EL; in rtC; in [-55.0°C to 50.0°C] [-67°F to 122°F] 0 to 120hours 0 to 255min rt; it; SEt; dEF	First probe used for defrost. If [dPA = nP] the regulation is performed by time Second probe used for defrost. If [dPb = nP] the regulation is performed with dPA. It defines the percentage of the dPA respect to dPb. The value used to regulate room temperature is obtained by: value_for_defrost= (dPA*dPE + dPb*(100-dPE))/100 EL = defrost with electrical heater; in = hot gas defrost. NOTE: The valve opening percentageduring the defrost is set by the par. oPd. rtC = defrost activation via RTC with Ld1, Ld2 parameters; in = defrost activation with idF parameter. Set the temperature measured by the evaporator probe dPA which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value; dEF = "dEF" label is visualized.
参 dd 参 tc 参 dd 参 dd 参 dd 参 dd	dPE tdF EdF dtE idF MdF dSd dFd dAd	100 EL in 8.0 6 45 0 rt 30	Defrost probe B Percentuale prima sonda sbrinamento Defrost kind. Defrost mode. End defrost temperature on probe A (dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request.	nP(0) - P1(1) - P2(2) - P3(3) - P4(4) - P5(5) 0 ÷ 100 (100=dPA, 0=dPb) EL; in rtC; in [-55.0°C to 50.0°C] [-67°F to 122°F] 0 to 120hours 0 to 255min 0 to 255min rt; it; SEt; dEF	Second probe used for defrost. If [dPb = nP] the regulation is performed with dPA. It defines the percentage of the dPA respect to dPb. The value used to regulate room temperature is obtained by: value_for_defrost= (dPA*dPE + dPb*(100-dPE))/100 EL = defrost with electrical heater; in = hot gas defrost. NOTE: The valve opening percentageduring the defrost is set by the par. oPd. rtC = defrost activation via RTC with Ld1, Ld2 parameters; in = defrost activation with idF parameter. Set the temperature measured by the evaporator probe dPA which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature (reading when defrost start); SEt = set-point value;
** to ** do	tdF EdF dtE idF MdF dSd dFd dAd	EL in 8.0 6 45 0 rt 30	sbrinamento Defrost kind. Defrost mode. End defrost temperature on probe A (dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request. Display during defrost.	0 ÷ 100 (100=dPA, 0=dPb) EL; in rtC; in [-55.0°C to 50.0°C] [-67°F to 122°F] 0 to 120hours 0 to 255min 0 to 255min rt; it; SEt; dEF	It defines the percentage of the dPA respect to dPb. The value used to regulate room temperature is obtained by: value_for_defrost= (dPA*dPE + dPb*(100-dPE))/100 EL = defrost with electrical heater; in = hot gas defrost. NOTE: The valve opening percentageduring the defrost is set by the par. oPd. rtC = defrost activation via RTC with Ld1, Ld2 parameters; in = defrost activation with idF parameter. Set the temperature measured by the evaporator probe dPA which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idf = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
· · · · · · · · · · · · · · · · · · ·	EdF dtE idF dSd dFd dAd	6 45 0 rt 30	Defrost mode. End defrost temperature on probe A (dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request. Display during defrost.	rtC; in [-55.0°C to 50.0°C] [-67°F to 122°F] 0 to 120hours 0 to 255min 0 to 255min rt; it; SEt; dEF	 in = hot gas defrost. NOTE: The valve opening percentageduring the defrost is set by the par. oPd. rtC = defrost activation via RTC with Ld1, Ld2 parameters; in = defrost activation with idF parameter. Set the temperature measured by the evaporator probe dPA which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 dd	dtE idF MdF dSd dFd dAd	8.0 6 45 0 rt 30	End defrost temperature on probe A (dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request. Display during defrost.	[-55.0°C to 50.0°C] [-67°F to 122°F] 0 to 120hours 0 to 255min 0 to 255min rt; it; SEt; dEF	in = defrost activation with idF parameter. Set the temperature measured by the evaporator probe dPA which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 id 参 dd 参 dd	idF MdF dSd dFd dAd	6 45 0 rt 30	(dPA). Defrost interval. (Maximum) duration for defrost. Defrost start delay after request. Display during defrost.	[-67°F to 122°F] 0 to 120hours 0 to 255min 0 to 255min rt; it; SEt; dEF	which stops the defrost. N.B.: parameter enabled only when the evaporator probe is present. It sets the time interval between the beginning of two defrost cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 M 参 dd 参 dd	MdF dSd dFd dAd	45 0 rt 30	(Maximum) duration for defrost. Defrost start delay after request. Display during defrost.	0 to 255min 0 to 255min rt; it; SEt; dEF	cycles. [EdF = in]: it is the interval between 2 defrost; [EdF = rtC]: it is the safety interval in case of clock alarm [RtC - RtF]. [idF = 0]: the defrost can be activated only manually, or through RS485 or from external contact or from LAN. When dPA in not present, it sets the defrost duration, otherwise it sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 dd 参 dd 参 f	dSd dFd dAd	0 rt 30	Defrost start delay after request. Display during defrost.	0 to 255min rt; it; SEt; dEF	sets the maximum duration for defrost. Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 dd	dFd dAd	rt 30	Display during defrost.	rt; it; SEt; dEF	Useful when different defrost start times are necessary to avoid overloading the plant. rt = real temperature for Lod probe; it = initial temperature (reading when defrost start); SEt = set-point value;
参 da	dAd	30	1 7 0		<pre>it = initial temperature (reading when defrost start); SEt = set-point value;</pre>
∰ F			Display delay.	0.1. 0551	
∰ di	Fdt	0		0 to 255min	Set the maximum time between the end of defrost and the restarting of the real room temperature display.
			Drain down time after defrost.	0 to 255min	Time interval between reaching defrost termination temperature and the restoring of the control's normal operation. This time allows the evaporator to eliminate water drops that might have formed due to defrost. The fan and the thermoregulation output are OFF during this time.
** 4	dPo	N	Defrost at power-on.	n; Y	First defrost after start-up: Y = Immediately; n = after the idF time.
·,,,, di	dAF	0.0	Defrost delay after continuous cycle.	0.0 to 24h00min (144)	Time interval between the end of the fast freezing cycle and the following defrost related to it. Format: hours.10min, resolution: 10min.
			FAN	»D(0): D4(4): D2(2):	First pushe used for far. If IFDA applishe regulation is performed
∳ FI	FPA	P2	Fan probe A	nP(0); P1(1); P2(2); P3(3); P4(4); P6(5)	First probe used for fan. If [FPA = nP] the regulation is performed with real value of FPb.
% Fi	FnC	O-n	Fan operating mode.	C-n; C-Y; O-n; O-Y	 C-n = running with the solenoid valve, OFF during the defrost; C-Y = running with the solenoid valve, ON during the defrost; O-n = continuous mode, OFF during the defrost; O-Y = continuous mode, ON during the defrost.
S F	Fnd	10	Fan delay after defrost.	0 to 255min	The time interval between the ending of the defrost and the starting of the evaporator fans.
% F	FCt	10.0	Temperature differential to avoid short cycles of fans.	[0.0°C to 50.0°C] [0°F to 90°F]	If the difference of temperature between the evaporator and the room probes is more than the value of the FCt parameter, the fans will start.
% F	FSt	10.0	Fan stop temperature.	[-55.0°C to 50.0°C] [-67°F to 122°F]	Evaporator probe temperature above which the fan is always OFF.
% FI	FHY	1.0	Fan stop differential	[0.1°C to 25.5°C] [1°F to 45°F]	When stopped, fan restarts when fan probe reaches [FSt - FHY] value of temperature.
% ti	tFE	N	Fan thermostat also during defrost	n; Y	 n = fan follows FnC setting during defrost without temperature control y = fan follows FnC setting during defrost with FSt temperature control
% F	Fod	0	Fan activation time after defrost (without compressor)	0 to 255min	It forces fan activation for the indicated time.
S F	Fon	0	Fan ON time	0 to 15min	With [FnC = C-n or C-Y] (fan activated in parallel with compressor), it sets the evaporator fan ON cycling time when the compressor is off. With [Fon = 0] and [FoF ≠ 0] the fan is always off, with [Fon = 0] and [FoF = 0] the fan is always off.
% F	FoF	0	Fan OFF time	0 to 15min	With [FnC = C-n or C-Y] (fan activated in parallel with compressor) it sets the evaporator fan off cycling time when the compressor is off. With [Fon = 0] and [FoF \neq 0] the fan are always off, with [Fon = 0] and [FoF = 0] the fan are always off.
⊭_ tı	trA	UAL	Kind of PWM regulation	UAL; rEG; AC	PWM output if CoM value is different from OA7. UAL = the output is at FSA value (manual value); rEG = the output is regulated with fan algorithm described in fan section; AC = anti-sweat heaters control (require XWEB5000 system).
⊬ s	SOA	0	Manual value of the analog output	AMi to AMA	Value for the output if [trA = UAL] (0 to 100%).
⊬ s	SdP	30.0	Default Dew-Point value (or safety value in case of XWEB link lost)	[-55.0°C to 50.0°C] [-67°F to 122°F]	Default value of dew-point used when there is no supervising system (XWEB5000). Used only if [trA = AC].
	ASr	1.0	Differential for fan / offset for anti sweat heater.	[-25.5°C to 25.5°C] [-45°F to 45°F]	trA = AC: dew-point offset; trA = rEG: differential for modulating fan regulation.
·	PbA	5.0	Proportional band for modulating output.	[0.1°C to 25.5°C] [1°F to 45°F]	Differential for anti-sweat heaters.
	AMi AMA	100	Minimum output for modulating output. Maximum output for modulating output.	0 to AMA AMi to 100	Minimum value for analog output: (0 to AMA). Maximum value for analog output: (AMi to 100).

	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
					trA = AC: Anti-sweat heaters cycle period;
K	AMt	5	Time with fan at maximum speed or ON time for relay on Anti-sweat regulation.	[10 to 60s] or [10 to 60min]	trA = rEG: Time with fan at maximum speed. During this time the fan works at maximum speed. If intended for fan, the basetime is on seconds, for anti-sweat regulation the basetime is on minutes.
			ALARM		
(1)	rAL	tEr	Probe for room temperature alarm.	nP; P1; P2; P3; P4; P6; tEr	It selects the probe used to signal alarm temperature.
(D)	ALC	rE	Room temperature alarm configuration:	rE; Ab	rE = High and Low alarms related to set-point;
(1)	ALU	15.0	relative to set point or absolute. High room temperature alarm setting.	[0.0°C to 50.0°C] or [ALL to 150.0°]	Ab = High and low alarms related to the absolute temperature. ALC = rE: [0.0°C to □50°C] or [32°F to 90°F]; ALC = Ab: [ALL to 150°C] or [ALL to 302°F]. When this temperature is reached and after the ALd delay time is
(D)	ALL	15.0	Low room temperature alarm setting.	[0.0°C to 50.0°C] or [-55.0°C to ALU]	expired, the HA alarm will be enabled. ALC = rE: [0.0°C to □50.0°C] or [32°F to 90°F]; ALC = Ab: [-55.0°C to ALU] or [-67°F to ALU]. After this temperature is reached and the ALd delay time is expired, the LA alarm will be enabled.
(1)	AHY	1.0	Differential for room temperature alarm.	[0.1°C to 25.5°C]	Threshold recovery after a temperature alarm.
			·	[1°F to 45°F]	Time interval between the detection of an alarm condition and the
(1)	ALd	15	Room Temperature alarm delay.	0 to 255min	corresponding alarm signaling.
(1)	dLU	150	High temperature alarm detected by defrost probe	[dLL ÷ 150.0°] [dLL ÷ 302°F]	When this temperature is reached and after the ddL delay time is expired, the HAd alarm will be enabled.
(1)	dLL	-50.0	Low room alarm detected by defrost probe.	[-55,0°C ÷ dLU] [-67°F ÷ dLU°F]	When this temperature is reached and the ddL delay time is expired, the LAd alarm will be enabled.
(1)	dHY	1.0	Differential for temperature alarm detected by defrost probe.	[0.1°C ÷ 25.5°C] [1°F ÷ 45°F]	Threshold recovery after a temperature alarm.
(1)	ddA	15	Delay of temperature alarm detected by defrost probe.	0 ÷ 255 (min.)	Time interval between the detection of an alarm condition and the corresponding alarm signaling.
(1)	FLU	150	High temperature alarm detected by fan	[FLL ÷ 150.0°] [FLL ÷ 302°F]	When this temperature is reached and after the FAd delay time is
	FLL	-50.0	probe Low room alarm detected by fan probe.	[-55,0°C ÷ FLU] [-67°F ÷	expired, the HAF alarm will be enabled. When this temperature is reached and the FAd delay time is expired the FAd alarm will be enabled.
(1)	FHY	1.0	Differential for temperature alarm	FLU°F] [0.1°C ÷ 25.5°C] [1°F ÷ 45°F]	expired, the FAd alarm will be enabled. Threshold recovery after a temperature alarm.
	FAd	15	detected by fan probe. Delay of temperature alarm detected by	0 ÷ 255 (min.)	Time interval between the detection of an alarm condition and the
	dAo	1.3	Delay of temperature alarm at start-up.	0.0 to 24h00min	corresponding alarm signaling. After powering on the instrument: time interval between the detection of the temperature alarm condition and the alarm alreading for the signal three dominance of the signal three domi
	EdA	20	Alarm delay at the end of defrost.	0 to 255min	signaling. Format: hours.10min, resolution: 10min. At the end of the defrost cycle: time interval between the detection of the temperature alarm condition and the alarm signaling.
(1)	dot	20	Temperature alarm exclusion after door open.	0 to 255min	- une temperature aiami condition and the aiami signaling.
(1)	Sti	nU	Stop regulation interval.	0.0 to 24h00min; nU	After regulating continuously for Sti time, the valve closes for Std time in order to prevent ice creation. Format: hours.10min, resolution: 10min.
(1)	Std	5	Stop duration.	1 to 255min	It defines stop regulation time after Sti. During this interval, the display shows StP message.
(1)	nMS	nu	Maximum number of regulation pauses.	"nu"(0) ÷ 255	-
(1)	tbA	Υ	Silencing alarm relay by pressing a key.	n; Y	-
			OUTPUT CONFIGURATION:		
	OA1	CPr	Relay on terminals 11-12 configuration	nU; CPr; dEF; FAn; ALr; LiG; AUS; db; onF; AC	nU = not used; CPr = compressor / valve; dEF = defrost; FAn = Fan; ALr = Alarm; LiG = Light; AUS = auxiliary; db = heater for neutral zone (not available with CrE = Y); onF = ON/OFF; AC = anti-sweet.; E3r: solenoid valve for EX3 or for mechanical solenoid valve
	OA6	AUS	Relay on terminals 17-18 configuration	nU; CPr; dEF; FAn; ALr; LiG; AUS; db; onF; AC	nU = not used; CPr = compressor / valve; dEF = defrost; FAn = Fan; ALr = Alarm; LiG = Light; AUS = auxiliary; db = heater for neutral zone (not available with CrE = Y); onF = ON/OFF; AC = anti-sweet.; E3r: solenoid valve for EX3 or for mechanical solenoid valve For models with PWM / O.C. output:
	CoM	CUr	Modulating output configuration.	PM5; PM6; OA7; CUr; tEn	- PM5 = PWM 50Hz; - PM6 = PWM 60Hz; - OA7 = two state, it can be used as an open collector output. For models with [4 to 20mA] or [0 to 10V] output: - Cur = 4 to 20mA current output; - tEn = 0 to 10V voltage output.
	АОР	CL	Alarm relay polarity.	OP; CL	CL = normally closed; OP = normally opened.
	iAU	n	Auxiliary output independent from ON/OFF state.	n; Y	n = if the instrument is switched off also the auxiliary output is switched off; Y = the auxiliary output state is unrelated to the ON/OFF device status.
			DIGITAL INPUTS		
ŤŤ	i1P	CL	Digital input 1 polarity.	OP; CL	CL = the digital input is activated by closing the contact; OP = the digital input is activated by opening the contact.
ŤŤ	i1F	dor	Digital input 1 configuration.	EAL; bAL; PAL; dor; dEF; AUS; LiG; OnF; Htr; FHU; ES; HdY	EAL = external alarm; bAL = serious external alarm; PAL = pressure switch activation; dor = door open; dEF = defrost activation; AUS = auxiliary activation; LiG = light activation; OnF = switch on/off the instrument; Htr = change type of action; FHU = not used; ES = activate energy saving; HdY = activate holiday function.

	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
	LAULL	TALUE	DECOMM HON	IMIVE	When [i1F = PAL]: time interval to calculate the number of the
ŤŤ	d1d	15	Digital input 1 activation delay.	0 to 255min	pressure switch activation. When [i1F = EAL or bAL] (external alarms): d1d parameter defines the time delay between the detection and the successive signaling of the alarm. When [i1F = dor]: this is the delay to activate door open alarm.
ŤŤ	i2P	CL	Digital input 2 polarity.	OP; CL	CL means the digital input is activated by closing the contact; OP means the digital input is activated by opening the contact.
ŤŤ	i2F	LiG	Digital input 2 configuration.	EAL; bAL; PAL; dor; dEF; AUS; LIG; OnF; Htr; FHU; ES; HdY	EAL = external alarm; bAL = serious external alarm; PAL = pressure switch activation; dor = door open; dEF = defrost activation; AUS = auxiliary activation; LiG = light activation; OnF = switch on/off the instrument; Htr = change type of action; FHU = not used; ES = activate energy saving; HdY = activate holiday function.
ŤŤ	d2d	5	Digital input 2 activation delay.	0 to 255min	When [i2F = PAL]: time interval to calculate the number of the pressure switch activation. When [i2F = EAL or bAL] (external alarms): d2d parameter defines the time delay between the detection and the successive signaling of the alarm. When [i2F = dor]: this is the delay to activate door open alarm.
ŤŤ	i3P	CL	Digital input 3 polarity.	OP; CL	CL means the digital input is activated by closing the contact;
rr				EAL; bAL; PAL;	OP means the digital input is activated by opening the contact. EAL = external alarm; bAL = serious external alarm; PAL = pressure switch activation; dor = door open;
ŤŤ	i3F	ES	Digital input 3 configuration.	dor; dEF; AUS; LiG; OnF; Htr; FHU; ES; HdY	dEF = defrost activation; AUS = auxiliary activation; LiG = light activation; OnF = switch on/off the instrument; Htr = change type of action; FHU = not used; ES = activate energy saving; HdY = activate holiday function.
ŤŤ	d3d	0	Digital input 3 activation delay.	0 to 255min	When [i3F = PAL]: time interval to calculate the number of the pressure switch activation. When [i3F = EAL or bAL] (external alarms): d3d parameter defines the time delay between the detection and the successive signaling of the alarm. When [i3F = dor]: this is the delay to activate door open alarm.
ŤŤ	nPS	15	Number of pressure switch activations before lock.	0 to 15	Number of activation of the pressure switch, during the d1d, d2d and d3d interval, before signaling the alarm event [i1F, i2F or i3F = PAL]. If the nPS activation in the d1d, d2d or d3d time is reached, switch off and on the instrument to restart normal regulation.
ŤŤ	OdC	F-C	Compressor and fan status when open door.	no; FAn; CPr; F-C	no = normal; Fan = Fan OFF; CPr = Compressor OFF; F_C = both Compressor and Fan OFF.
ŤŤ	rrd	15	Output restart delay with door open.	0 to 255min	The outputs stopped by the OdC parameter can restart after rrd time.
			ENERGY SAVING		unio.
(ESP	P1	Energy saving probe selection.	nP; P1; P2; P3; P4; P6; tEr	-
(()	HES	0.0	Temperature increasing during Energy Saving.	[-30.0°C to 30.0°C] [-54°F to 54°F]	Sets the increasing value of the set point during the Energy Saving cycle.
*)	PEL	nU	Energy saving activation when Light or/and AUX are switched off.	nU(0); LIG(1); AUS(2); LEA(3)	Energy saving enabled when: - LiG: light switched off; - AUS: AUX switched off; - LEA: both light and AUX switched off. If nU then not used function.
			LAN MANAGEMENT		
望	LMd	Y	Defrost Synchronization.	n; Y	n = the section doesn't send a global defrost command; Y = the section sends a command to start defrost to other controllers.
**	dEM	Y	Defrost end Synchronization.	n; Y	n = the end of the LAN defrosts are independent; Y = the end of the LAN defrosts are synchronized.
***	LSP	n	LAN set-point Synchronization.	n; Y	n = the set-point value is modified only in the local section; Y = the section set-point, when modified, is updated to the same value on all the other sections.
鞶	LdS	n	LAN Display Synchronization (temperature sent via LAN).	n; Y	n = the set-point value is modified only in the local section; Y = the value displayed by the section is sent to all the other sections.
鞶	LOF	n	LAN ON/OFF Synchronization.	n; Y	This parameter states if the On/Off command of the section will act on all the other ones too: n = the On/Off command acts only in the local section; Y = the On/Off command is sent to all the other sections.
**	LLi	Y	LAN Light Synchronization.	n; Y	This parameter states if the light command of the section will act on all the other ones too: n = the light command acts only in the local section; Y = the light command is sent to all the other sections.
**	LAU	n	AUX Synchronization.	n; Y	This parameter states if the AUX command of the section will act on all the other ones too: n = the light command acts only in the local section; Y = the light command is sent to all the other sections.
鞶	LES	n	Energy Saving Synchronization.	n; Y	This parameter states if the energy saving command of the section will act on all the other ones too: n = the Energy Saving command acts only in the local section; Y = the Energy Saving command is sent to all the other sections.
鞶	LSd	n	Remote probe displaying.	n; Y	This parameter states if the section has to display the local probe value or the value coming from another section: n = the displayed value is the local probe one; Y = the displayed value is the one coming from another section (which has parameter LdS = Y).
왐	LPP	Y	Pressure probe through the LAN.	n; Y	n = the value of pressure probe is read from local probe; Y = the value of pressure probe is sent via LAN.
왐	LCP	n	Probe 4 through the LAN.	n; Y	The state of the s

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	LABEL	VALUE	DESCRIPTION	RANGE	NOTES
**	StM	n	Cooling request from LAN enable compressor relay.	n; Y	 n = not used; Y = a generic cooling requests from LAN activate the solenoid valve connected to compressor relay.
鞶	ACE	n	Cooling request from LAN enable even if compressor is stopped by door switch	n; Y	 n = not used; Y = a generic cooling requests from LAN activate the solenoid valve connected to compressor relay.
			PROBE CONFIGURATION NTC (10KΩ a 25°C), PtC (806Ω a 0°C)		
₽	P1C	ntC	P1 configuration.	nP; PtC; ntC; CtC; PtM	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US PtM = Pt1000.
身	Ot	0	P1 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the thermostat probe.
Ø	P2C	ntC	P2 configuration.	nP; PtC; ntC; CtC; PtM	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US PtM = Pt1000.
身	οE	0	P2 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the evaporator probe.
身	P3C	nP	P3 configuration.	nP; PtC; ntC; CtC; PtM	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US PtM = Pt1000.
₽	03	0	P3 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the probe 3.
身	P4C	nP	P4 configuration.	nP; PtC; ntC; CtC; PtM; LAN	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US PtM = Pt1000; LAN = value received from master.
身	04	0	P4 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the probe 4.
\$	P5C	420	P5 configuration.	nP; PtC; ntC; CtC; PtM; 420; 5Vr; LAN	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US; PtM = Pt1000; 420 = 4 to 20mA; 5Vr = 0 to 5V ratiometric; LAN = value received from master.
身	о5	0	P5 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the probe 5.
身	P6C	PtM	P6 configuration.	nP; PtC; ntC; CtC; PtM	nP = not present; PtC = Ptc; ntC = ntc; CtC = ntc US PtM = Pt1000.
Ø	о6	0	P6 calibration.	[-12.0°C to 12.0°C]	Allows to adjust possible offset of the probe 6.
			SERVICE		
	CLt		ON/OFF percentage (C.R.O.).	(read only)	It shows the effective cooling time calculated by XM600 during regulation (cooling time percentage).
	tMd		Time remaining before next defrost activation (only for interval defrost).	(read only)	It shows time before the next defrost when interval defrost is selected.
	LSn	Auto	Number of devices in LAN.	1 to 8 (read only)	Shows the number of sections available in the LAN.
	LAn	Auto	List of address of LAN devices.	1 to 247 (read only)	Identifies the instrument address (1 to LSn) inside local network of multiplexed cabinet controller.
	Adr	1	ModBUS address.	1 to 247	Identifies the instrument address when connected to a ModBUS compatible monitoring system.
	rEL	2.6	Firmware release.	(read only)	Microprocessor firmware release.
	Ptb		Parameter table.	(read only)	It shows the original code of the Dixell parameter map.
	Pr2		Pr2 menu access.	(read only)	Access to the protected parameter list.

Dixell°



Dixell S.r.l. - Z.I. Via dell'Industria, 27 - 32010 Pieve d'Alpago (BL) ITALY Tel. +39.0437.9833 r.a. - Fax +39.0437.989313 - EmersonClimate.com/Dixell - dixell@emerson.com